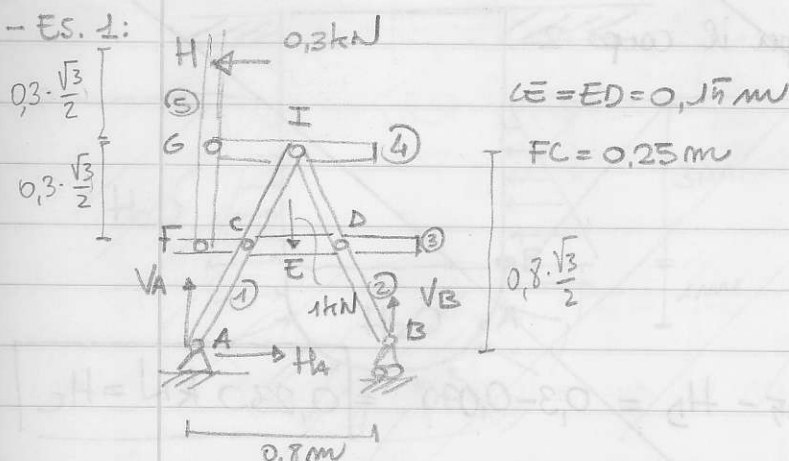


REAZ. VINC:

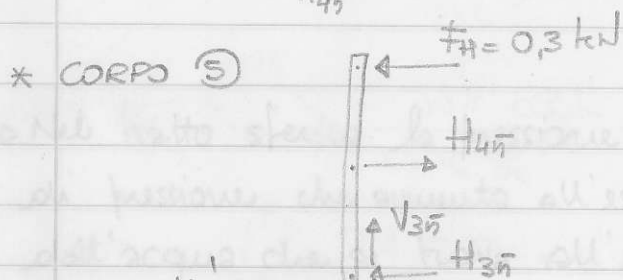
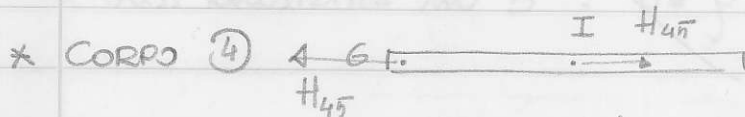


$$V_A + V_B = F_E = 1 \text{ kN}$$

$$H_A = F_H = 0,3 \text{ kN}$$

$$\Rightarrow V_B = \frac{0,4 - 0,3 \cdot (0,95)}{0,8} = \underline{\underline{0,142 \text{ kN}}}$$

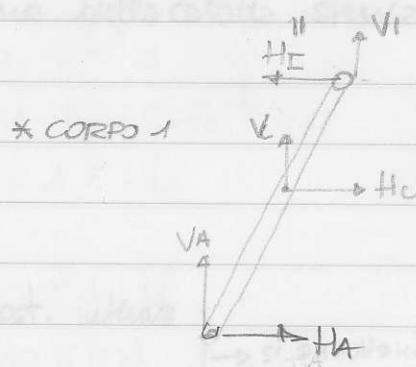
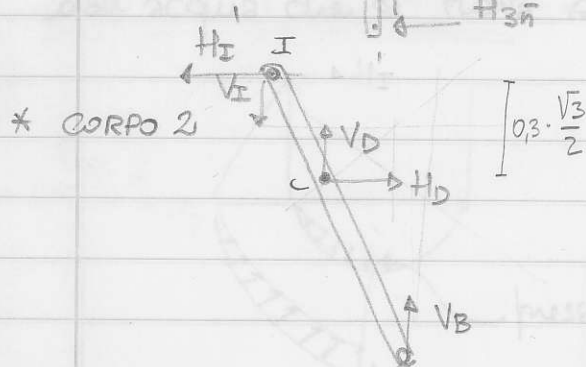
$$\Rightarrow \underline{V_A = 0,858 \text{ kN}}$$



$$\Rightarrow V_{35} = 0$$

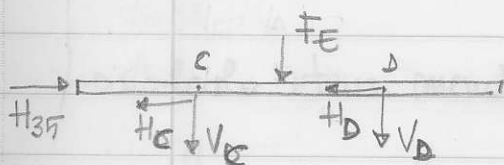
$$\Rightarrow H_{4n} = 2F_H = 0,6 \text{ kN}$$

$$\Rightarrow H_{35} = 0,3 \text{ kN}$$



$$H_1' + H_2 = H_{45} = 0,6 \text{ kN}$$

* CORPS ③



$\Rightarrow$ Eq. mom C

$$-F_E \cdot 0,15 - V_D \cdot 0,3 = 0$$

$$\Rightarrow V_D = -\frac{F_E}{2} = \boxed{-0,5 \text{ kN} = V_D}$$

$$-V_D - F_E - V_C = 0 \Rightarrow V_C = -F_E - V_D = -1 + 0,5 = -0,5 \text{ kN} = V_C$$

Eq. mom. corp/2 risp. I

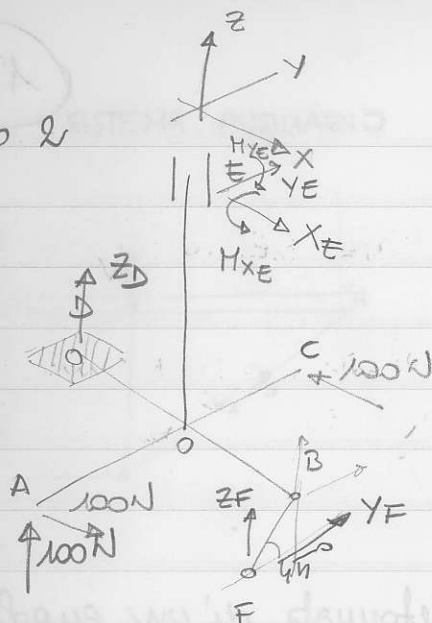
$$-V_D \cdot 0,15 + V_B \cdot 0,4 + H_D \cdot 0,3 \cdot \frac{\sqrt{3}}{2} = 0 \Rightarrow H_D = 0,07 \text{ kN}$$

$$H_C = 0,23 \text{ kN}$$

(2)

SERIZIO 2

Determina reazioni vincolari



$$\leftarrow Z_F = Y_F \quad (1^a \text{ eq})$$

Eq. lungo z:

$$100 + Z_F + Z_D = 0$$

lungo x

$$X_E = 0$$

lungo y

$$Y_F + Y_E = 0$$

Rot. int x (polo O)

$$-100 \times 1 - Y_E \cdot 1 + M_{XE} = 0$$

Rot. int y (polo O)

$$+ Z_D \cdot 1 - Z_F \cdot 1 + X_E \cdot 1 + M_{YE} = 0$$

Rot. intorno z (polo O)

$$200 \times 1 + M_{ZF} \cdot 1 = 0$$

$$\Rightarrow M_{ZF} = -200 \text{ Nm}$$

$$Z_F = -200 \text{ N}$$

$$Y_E = 200 \text{ N}$$

$$X_E = 0 \text{ N}$$

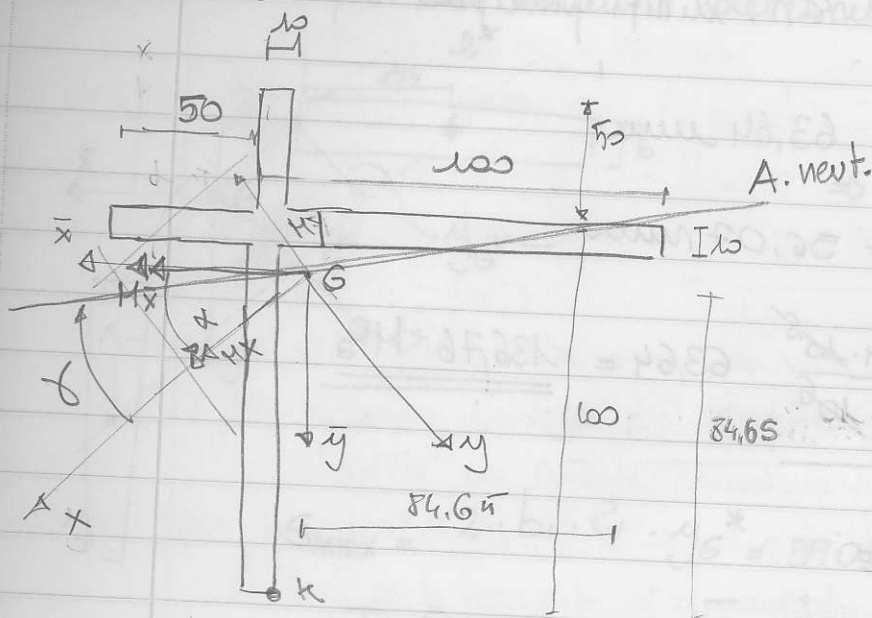
$$Z_D = 100 \text{ N}$$

$$M_{XE} = 300 \text{ Nm}$$

$$M_{YE} = -300 \text{ Nm}$$

ESERCIZIO 3

(3)



$$T_{\bar{x}} = 3 \text{ kN}$$

$$T_{\bar{y}} = -3 \text{ kN}$$

$$J_{\bar{x}} = J_{\bar{y}} = 3,11 \cdot 10^6 \text{ mm}^4$$

$$J_{\bar{x}\bar{y}} = 3,1 \cdot 10^5 \text{ mm}^4$$

→ Assi principali: da questioni di simm., $\alpha = 45^\circ$, x e y nuovi assi principali

⇒ Nuovi valori dei mom. d'inertia rispetto gli assi principali

$$J_x = J_{\bar{x}} \cdot \cos^2 \alpha - J_{\bar{x}\bar{y}} \sin \alpha \cos \alpha + J_{\bar{y}} \sin^2 \alpha = 2,8 \cdot 10^6 \text{ mm}^4 = J_x$$

$$J_y = J_{\bar{y}} \cos^2 \alpha + J_{\bar{x}\bar{y}} \sin \alpha \cos \alpha + J_{\bar{x}} \sin^2 \alpha = 3,42 \cdot 10^6 \text{ mm}^4 = J_y$$

FLESSIONE: Ho $M_{\bar{x}} = 5 \text{ kNm}$;

$$M_x = M_{\bar{x}} \cdot \cos \alpha = 3,54 \text{ kNm}$$

$$M_y = -M_x \cdot \sin \alpha = -3,54 \text{ kNm}$$

ASSE NEUTRO,

$$0 = \frac{M_x}{J_x} \cdot y - \frac{M_y}{J_y} \cdot x$$

$$y = \frac{M_y}{M_x} \cdot \frac{J_x}{J_y} = -1 \cdot \frac{2,8 \cdot 10^6}{3,42 \cdot 10^6} = \boxed{-0,819 x = y} \quad \leftarrow \text{eq. asse neutro}$$

$$-\alpha = \arctan(-0,819) \Rightarrow \boxed{39,3^\circ = \alpha}$$

Calcolo tensione σ_z nel punto + sol. (k, + lontano dall'asse neutro)

k (5,35; 84,65) nel sistema iniziale

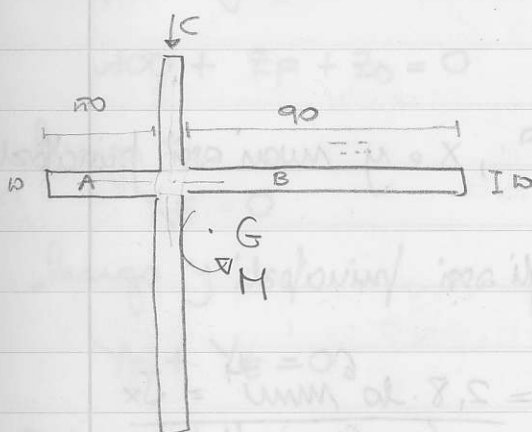
Scivo le coord. di k nel nuovo sist. di rif. principale

$$x = \bar{X}(k) \cdot \cos \alpha + \bar{Y}(k) \cdot \sin \alpha = 63,64 \text{ mm}$$

$$y = -\bar{X}(k) \cdot \sin \alpha + \bar{Y}(k) \cdot \cos \alpha = 56,07 \text{ mm}$$

$$\sigma_z(k) = \frac{3,54 \cdot 10^6}{2,8 \cdot 10^6} \cdot 56,07 + \frac{3,54 \cdot 10^6}{3,42 \cdot 10^6} \cdot 63,64 = \underline{\underline{136,76 \text{ MPa}}}$$

→ EFFETTO MOMENTO TORCENTE



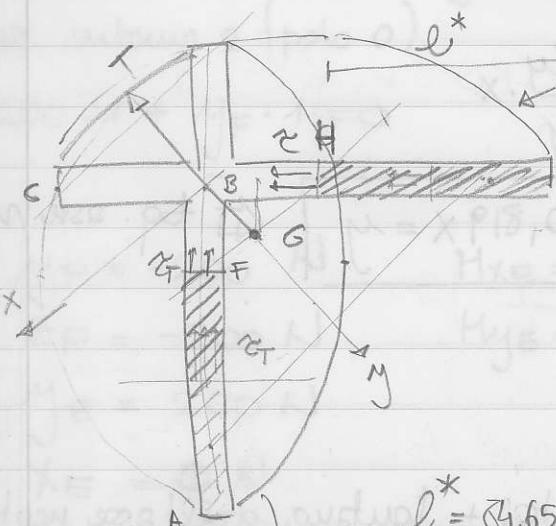
→ le tensioni tangenziali, per una sez. NON TUBOLARE, si determinano come

$$\tau_{M_T} = \frac{\max 3 M_z \cdot s}{\sum l_i s_i^3}$$

$$\tau_{\max} = \frac{3 \cdot M \cdot 10}{10^3 \cdot (50 + 90 + 10 + 50 + 90)} = \frac{3M}{2,9 \cdot 10^4} = 1,034 \cdot 10^{-4} M \text{ N/mm}^2$$

con Min Nmm

→ EFFETTO DEL TAGLIO (calcolato con Jourawsky) -



$$T_y = -\sqrt{T_x^2 + T_y^2} = \underline{\underline{-3 \cdot \sqrt{2} \text{ kN}}}$$

$$\tau_{T(AB)} = \frac{T \cdot S}{2 b \cdot J_x}$$

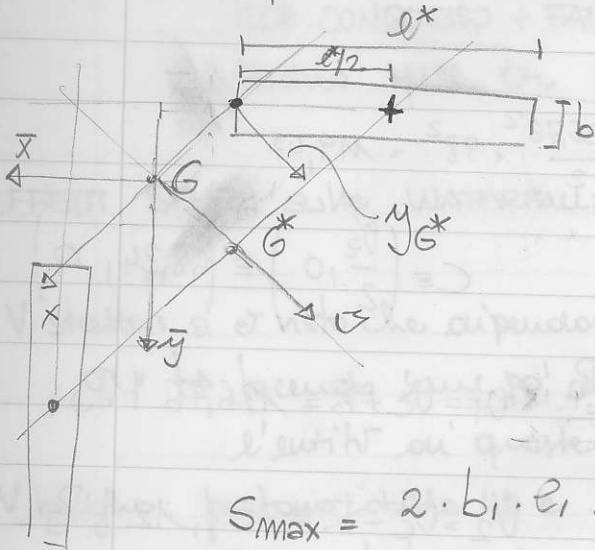
→ Viene massima nel punto F (o H)

$$l^* = 81,65 - (5,35 + 5) = \underline{\underline{71,30 \text{ mm}}}$$

2nd. e lungo asse verticale

(5)

Determino la pos. del baricentro dei 2 rettangoli (G')



$$\Rightarrow y_{G'}^* = \frac{e^*}{2} \cdot \frac{\sqrt{2}}{2} = 37,15 \cdot \frac{\sqrt{2}}{2} = \underline{\underline{26,25 \text{ mm}}}$$

$$S_{\max} = 2 \cdot b_1 \cdot e_1 \cdot y_{G'}^* = 39035 \text{ mm}^3$$

$$\tau_{\max} = \frac{T \cdot S_{\max}}{2b \cdot J_x} = \frac{3 \cdot \sqrt{2} \cdot 10^3 \cdot 39035}{2 \cdot 10 \cdot 2,8 \cdot 10^6} = \underline{\underline{2,95 \text{ MPa}}}$$

Le tensioni da taglio vengono quindi trascurabili - il punto + caricato rimane quindi il punto k

$$\sigma_z(k) = 136,76 \text{ MPa}$$

$$\tau_{H_T}(k) = 1,034 \cdot 10^{-1} \text{ M (MPa)} \leftarrow \text{ipotesi che sia coincidente con k il punto + sollecitato}$$

Taglio nullo

$$\sigma_{\text{eq}} = \sqrt{\sigma_z^2 + 4 \tau_{\max}^2} = \frac{\sigma_{\text{amm}}}{C_s}$$

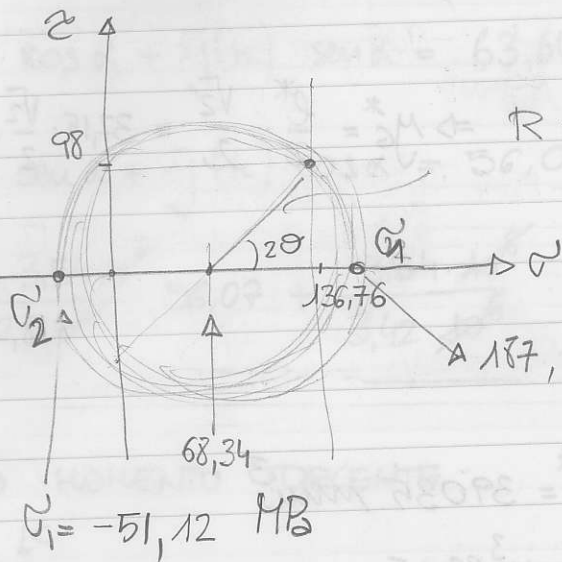
$$\left(\sigma_z^2 + 4 \tau_{\max}^2 \right) \cdot 1,25^2 = 300^2$$

$$4 \tau_{\max}^2 = \left(\frac{300}{1,25} \right)^2 - \sigma_z^2$$

$$\tau_{\max} = \frac{1}{2} \cdot \sqrt{\left(\frac{300}{1,25} \right)^2 - \sigma_z^2} = 98,61 \text{ MPa}$$

$$M = \frac{\tau_{\max}}{1,034 \cdot 10^{-1}} = \underline{\underline{953 \text{ Nm}}}$$

GERAM DI MOHR:

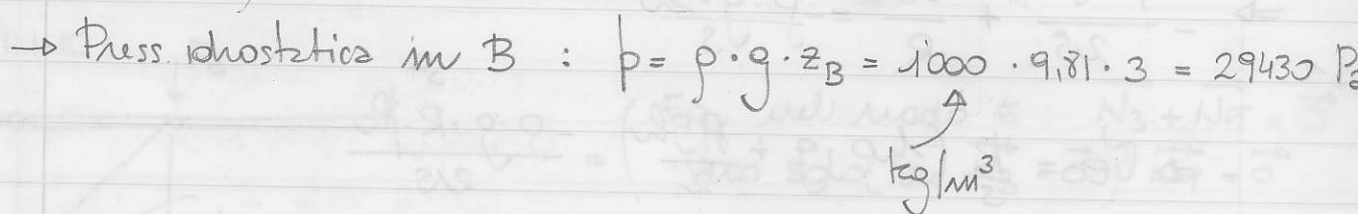


$$R = \sqrt{\left(\frac{136,76}{2}\right)^2 + 98^2} = 119,47$$

$$C = \left(\frac{\sigma_1 + \sigma_2}{2}, 0\right) = (68,34, 0)$$

$$\sigma_1 = \sigma_c + R = 136,76 \text{ MPa}$$

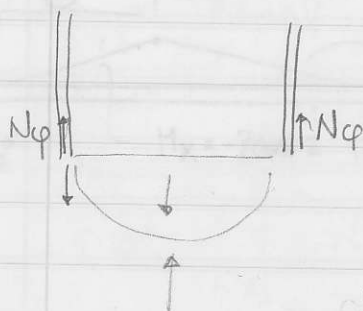
$$\sigma_2 = \sigma_c - R = -51,12 \text{ MPa}$$





pressione idrost. interna
 } → si annullano.
 pressione idrost. esterna

→ Czeło tus. membranli in B:

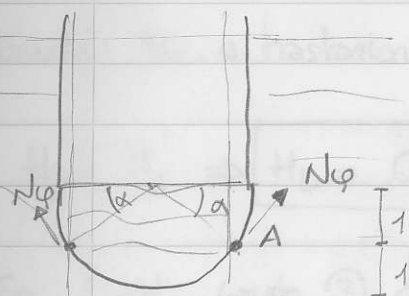


$$-2\cancel{R} \cdot s \cdot \sigma_{\varphi} = -\ln p \cdot \cancel{R}^2 \cdot g \Rightarrow \sigma_{\varphi} = \frac{p g R \ln}{2s} = 29,81 \text{ MP}$$

$$\frac{\cancel{\sigma_{\phi}}}{R_{\phi}} + \frac{\sigma_{\theta}}{R_{\theta}} = -\frac{p}{s} \Rightarrow \sigma_{\theta} = \frac{-p g R_{\theta} \cdot h}{s} = -19,62 \text{ MPa}$$

8

→ Calcolo ora le tensioni nel punto A



$$\rightarrow N_{\phi} \cdot 2R \cos \alpha = -R^2 \cdot \rho \cdot g \cdot h \cdot \cos \alpha$$

$$\rightarrow V_{\phi} = -\frac{\rho \cdot g \cdot R \cdot h}{2S}$$

$$\frac{V_{\phi}}{R_{\phi}} + \frac{V_{\theta}}{R_{\theta}} = \frac{\Delta P}{S} = -\frac{\rho \cdot g \cdot h}{S}$$

$\Delta P: P_{int} - P_{ext}$

$$\Rightarrow -\frac{\rho \cdot g \cdot h}{2S} + \frac{V_{\theta}}{R} = -\frac{\rho \cdot g \cdot h}{S}$$

$$\Rightarrow V_{\theta} = \frac{R}{S} \left(-\frac{\rho \cdot g \cdot h}{2} + \frac{\rho \cdot g \cdot h}{S} \right) = -\frac{\rho \cdot g \cdot R \cdot h}{2S}$$

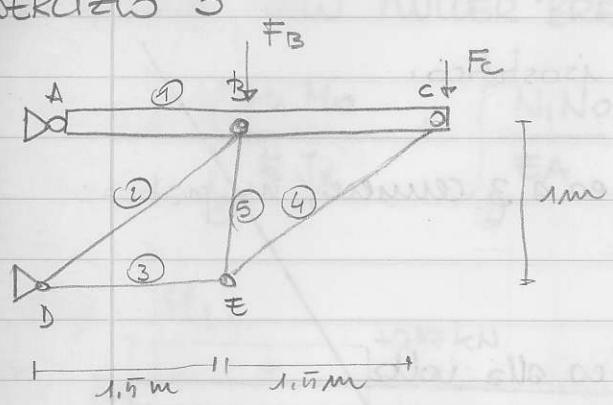
$$\Rightarrow V_{\theta A} = -\frac{\rho \cdot g \cdot R \cdot h}{2S} = \frac{-1000 \cdot 9.81 \cdot 2 \cdot 3}{2 \cdot 3 \cdot 10^{-3}} = -9.81 \cdot 10^6 \text{ Pa} = \underline{\underline{-9.81 \text{ MPa}}}$$

$$V_{\phi(A)} = -\frac{\rho \cdot g \cdot R \cdot h}{2S} = V_{\theta} = \underline{\underline{-9.81 \text{ MPa}}}$$

$$V_{\theta} = \frac{\rho \cdot g \cdot R \cdot h}{2S} = \frac{1000 \cdot 9.81 \cdot 2 \cdot 3}{2 \cdot 3 \cdot 10^{-3}} = 9.81 \cdot 10^6 \text{ Pa} = \underline{\underline{9.81 \text{ MPa}}}$$

$$V_{\phi} = \frac{\rho \cdot g \cdot R \cdot h}{2S} = \frac{1000 \cdot 9.81 \cdot 2 \cdot 3}{2 \cdot 3 \cdot 10^{-3}} = 9.81 \cdot 10^6 \text{ Pa} = \underline{\underline{9.81 \text{ MPa}}}$$

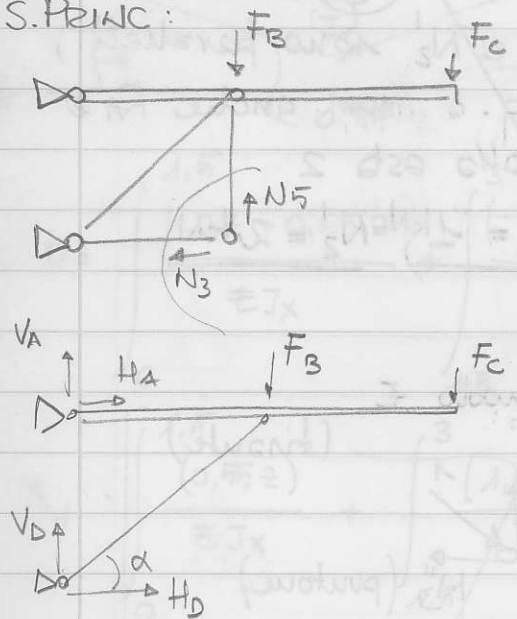
ESERCIZIO 5



→ Determinare la forza in CE

→ Sist. 1 volta iperstatico ⇒ lo rendo isostatico smuovendo l'asta EC

S.PRINC:



Eq. del nodo E: $\vec{N}_3 + \vec{N}_5 = \vec{0}$
 vero solo se $\vec{N}_3 = \vec{0}$; $\vec{N}_5 = \vec{0}$

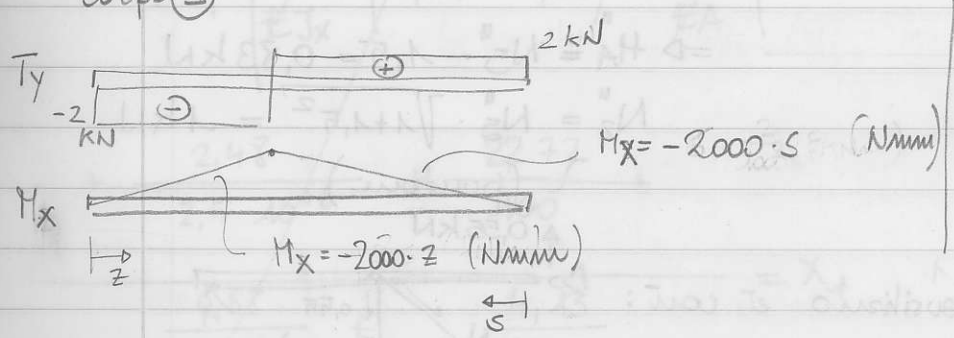
le aste 3 e 5 sono sciolte

$$\begin{cases} V_A + V_D = F_B + F_C \\ H_A + H_D = 0 \\ -H_A \cdot 1 - F_B \cdot 1,5 - F_C \cdot 3 = 0 \\ H_D = 1,5 \cdot V_D \end{cases}$$

$$\begin{cases} H_A = -10,5 \text{ kN} \\ H_D = +10,5 \text{ kN} \\ V_D = 7 \text{ kN} \\ V_A = -2 \text{ kN} \end{cases} \Rightarrow N_2 = \sqrt{7^2 + 10,5^2} = 12,62 \text{ kN}$$

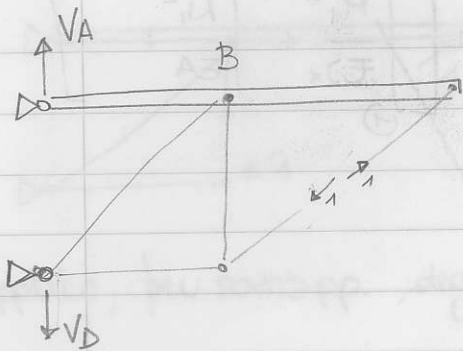
portante

Coppia (1)



5-2

SISTEMA AUSILIARIO



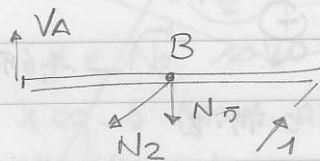
Globalmente il sistema è soggetto ad un sistema di forze con risultante nulla (anche per i momenti).

→ Le reazioni vincolari quindi dovranno essere un sist. di forze diretto in direz. verticale e contrapposte.

→ Eq. (1) (a mom. rispetto B)

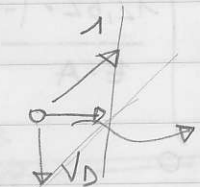
$$V_A \cdot 1,5 = 1 \cdot 1,5 \cdot \frac{1}{\sqrt{1^2 + 1,5^2}} = 0,55 \text{ N}$$

$$V_D = 0,55$$



$$N_2 = 1 \text{ N (da eq. a haslet. in dir. opp. a 1)}$$

→ Nodo D



$$N_3 = -0,83 \text{ N}$$

$$N_5 = 0,55 \text{ N}$$

RICAPITOLANDO

ASTA	S. PRINC.	S. ADS
②	12'620 N (P)	1 N (T)
③	SCARICA	0,83 N (P)
④	"	0,55 N (T)
⑤	"	1 N (P)

$$\delta_{1P} = 2 \cdot \int_0^{1500} \frac{-2000 \cdot 0,55 \cdot z^2}{EJ_x} dz + \int_0^{1803} \frac{-12620 \cdot 1 dz}{EA} = -4,95 - 1,14 = -6,09 \text{ mm}$$

$$\delta_{11} = 2 \cdot \int_0^{1500} \frac{0,55^2 z^2 dz}{EJ_x} + 2 \cdot \frac{1 \cdot 1803}{EA} + \frac{0,55^2 \cdot 1000}{E \cdot A} + \frac{0,83^2 \cdot 1500}{EA} =$$

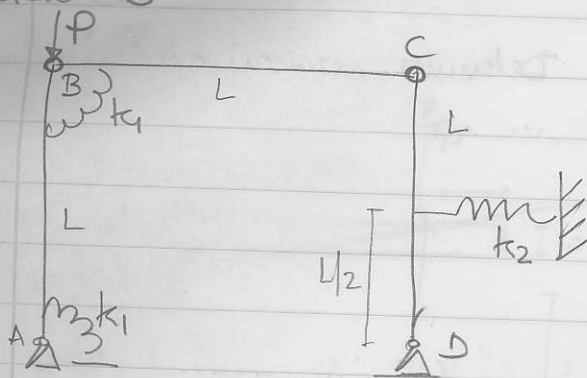
$$= 0,00136 + 0,00025 = 0,0016 \text{ mm}$$

$$X_1 = -\frac{\delta_{1P}}{\delta_{11}} = + \frac{6,09}{0,0016} = +3790$$

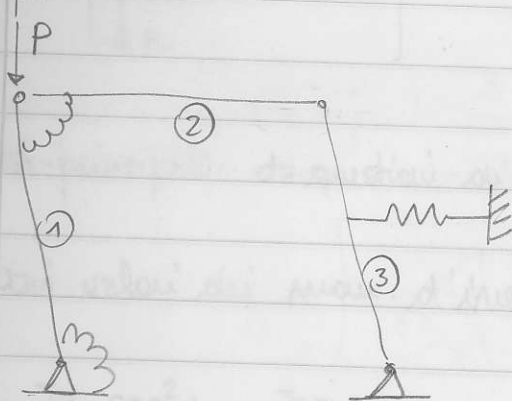
$$\boxed{N_4 = +3790 \text{ N}}$$

ESERCIZIO 6

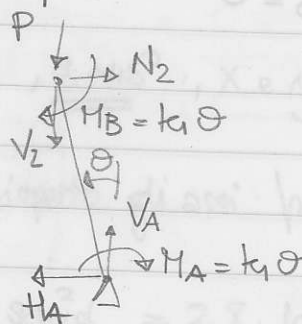
12



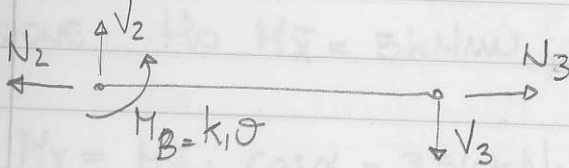
Considero corpi rigidi e una conf. deformata di un angolo θ piccolo



Eq. corpo 1

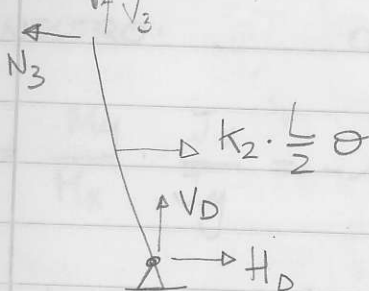


Corpo 2



$$\begin{cases} V_2 = V_3 \\ V_3 = \frac{M}{L} = \frac{k_1 \theta}{L} \\ N_2 = N_3 \end{cases}$$

Corpo 3



$$\begin{aligned} N_3 \cdot L - V_3 \cdot L \theta - k_2 \frac{L^2}{4} \theta &= 0 \\ \Rightarrow N_3 &= \left(V_3 + \frac{k_2 L}{4} \right) \theta = \\ &= \left(\frac{k_1 \theta}{L} + \frac{k_2 L}{4} \right) \theta \end{aligned}$$

Ritorno all'eq. corpo 1 anal. intorno ad A

$$P = \frac{9}{4} k_2 L$$

$$P \cdot L \cdot \theta + V_2 L \cdot \theta + 2k_1 \theta - \frac{k_1 \theta^2}{L} - \frac{k_2 \theta^2}{4} = 0$$

$$P \cdot L \cdot \theta + k_1 \theta - 2k_1 \theta - k_1 \theta^2 - \frac{k_2 \theta L^2}{4} = 0 \Rightarrow P = 2k_1 + \frac{k_2 L^2}{4} = \frac{9}{4} k_2 L^2$$